

The Effect of Guided Growth on Rotational Deformities of the Long Bones: A Biomechanical Study on Sawbone

Emre Cullu¹, Mutlu Cobanoglu^{2*}, Mustafa Kemal Peker³

Abstract

Background: Although temporary hemi-epiphysiodesis is an effective method for correction of frontal and sagittal plane limb deformity in growing children, osteotomy is commonly performed to correct rotational deformities of the long bones. The aim of this report is to improve rotational guided growth with a formula created to calculate the amount of correction.

Methods: A femur sawbone was cut above the trochlear sulcus. Two 8-plates were placed opposite to each other on medial and lateral sides of the cutting line. Three pairs of holes were drilled in three different angles on medial side and lateral side to place two plates on sawbone. The bone was distracted by an intramedullary device. The anteversion angles were measured by computerized tomography. The angles between the femoral axis and the plates were measured on X-ray. A formula was used to calculate the amount of correction.

Results: As the bone was distracted, rotation of the distal part of the cutting line was observed. When the angles between the plates and the long axis of the bone (α) were 50°, 36°, and 26°, the axial rotations were -11.25°, 2.43°, and 7.06° respectively on CT. When the formula was applied, the amounts of corrections were 25.7°, 18.5°, and 13.4° respectively.

Conclusions: This study supports that this technique can be used for correction of rotational deformities of the long bones. It's said that the wider angle between the plates and the long axis of the bone, the greater rotation. But further experimental studies are required to improve this technique.

Key Words: rotational guided growth, rotational deformity, temporary epiphysiodesis

Introduction

There are many options for the correction of angular bone deformities but the standard treatment has been osteotomy. Currently, hemi-epiphysiodesis is considered an effective treatment to correct an axial limb deformity in children [1,2] and Stevens presented a technique using an 8-plate [3]. Although this technique is an effective treatment method for correction of frontal and sagittal plane limb deformities in growing children, osteotomy is still a commonly used surgical technique for rotational deformities of the long bones. In the recent years, it has been thought that a rotational deformity in the horizontal plane of the long bones could be corrected by guided growth and two animal studies, which evaluated guiding rotational growth,

were published [4,5].

In this biomechanical study the aim was to improve rotational guided growth with a formula created to calculate the amount of correction. Because of that a sawbone model was designed.

Materials and Methods

One femur foam cortical shell sawbone with a 15 mm diameter canal and 42 cm overall length was used for the model. A left femoral sawbone, two titanium growth 8-plates (Biomet/USA and TST/Turkey), a distractor of an external fixator, a steel spring, a handle of an umbrella were used to construct this model. The sawbone was cut just above the intercondylar sulcus. This cutting line acted as a physal line. The sawbone was reamed from the fossa

priformis with a 12-mm drill for the placement of an intramedullary device to distract the fragments. The sharp ends of the distractor were cut. The distractor, the handle of the umbrella, and the spring were placed into the medullary canal via fossa priformis and fixed with glue gun. The outer part of the handle was cut and used as an antirotation block in the canal. The block was glued to the sawbone through a window opened from posterior surface of the proximal side of the cutting line. This block prevented the rotation of the distractor in the canal. The tip of the spring was fixed with glu to the distal fragment. This spring was placed between proximal and distal fragments. When the device was distracted, the device pushed the spring toward the distal fragment. By this way the

lengthening was obtained. Because of the spring, distractor did not create an external rotation force on the distal fragment by itself directly (Figure 1). Three pairs of holes were drilled in three different angles to place plates on the sawbone, Two 8-plates, whose brands were different, with four screws were used to fix the cutting line and were placed on medial and lateral side of the bone

(Fig 2). The different plates of different brands were helpful to differentiate one

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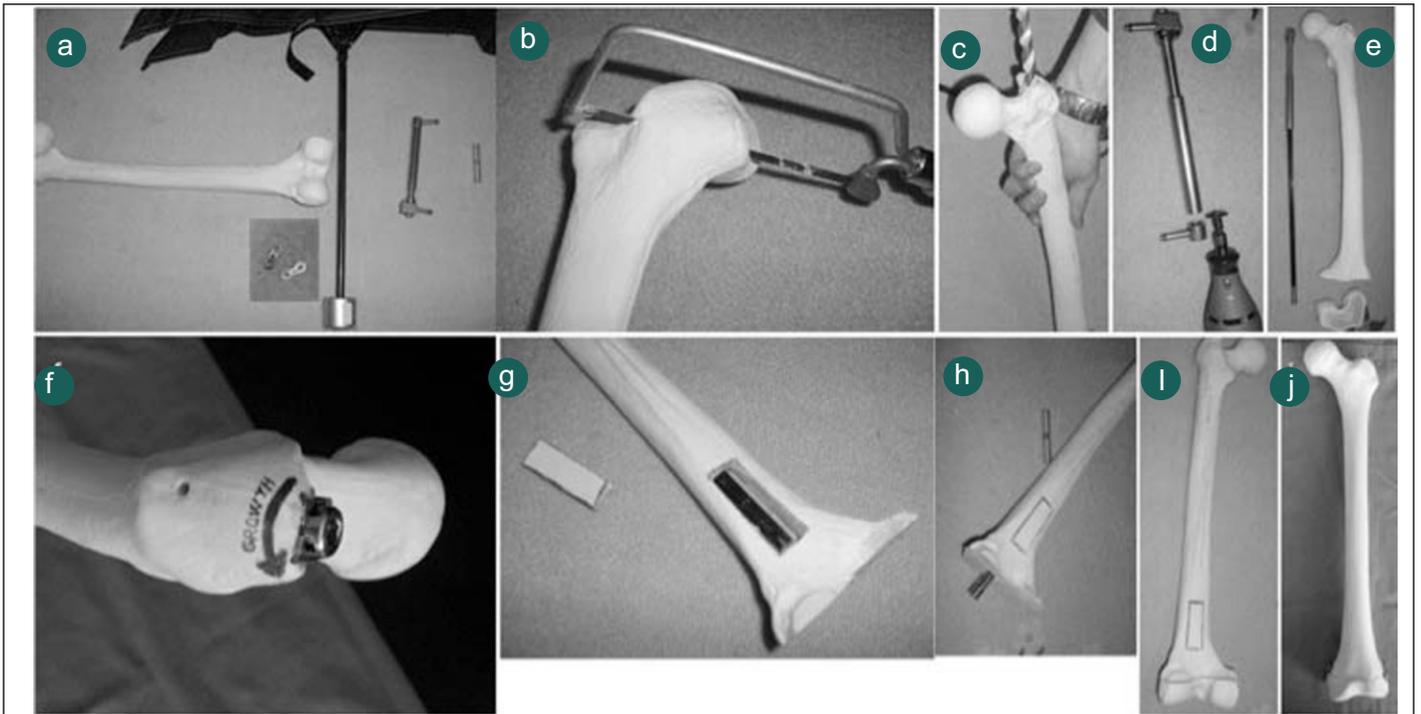


Figure 1- a) A left femoral sawbone, two 3.5mm titanium 8-plates (waste materials), a distractor from an old external fixator, a steel spring, an old umbrella b) the sawbone was cut just above the intercondylar sulcus, c) the sawbone was reamed with a 12-mm drill for placement of an intramedullary device, d) the sharp ends of the distractor were cut, e) the distractor, the handle of the umbrella, and the spring were placed into f) the medullary canal via fossa priformis and fixed using the glue gun, g) the outer part of the handle was cut and used as an antirotation bearing in the distal femur, h) the bearing was glued to the sawbone through a window on the posterior surface of the proximal region of the bone near the cutting line, i) the tip of the spring was glued to the distal fragment, j) and two plate were placed on the medial and lateral surface of the bone.



Figure 2- Model showing the cutting line, two 8-plates, and an intramedullary-lengthening device

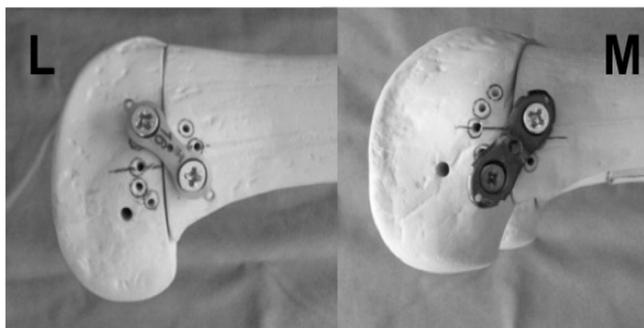


Figure 3- View of the plates on the lateral (L, left) and medial (M, right) sides

plate from the other on lateral X-ray. To create external rotation the medial plate was placed obliquely from the proximal anterior region to the distal posterior region, and the lateral plate was placed obliquely from the proximal posterior region to the distal anterior region (Figure 3). Fixation of the plates was performed in three different angles. The screws were not tightened completely. An allen wrench was used to distract the intramedullary device on its proximal end.

The distances between proximal and distal holes were measured in each plate manually. The angles between the femoral axis and the plates were measured on lateral X-ray. Femoral length (FL) (from the tip of trochanter major to top of intercondylar notch), mechanical lateral distal femoral angle (mLDFA), anatomic posterior distal femoral angle (aPFDA) were evaluated on computerized tomography (CT) scanogram. The femoral anteversion of the sawbone was measured on CT. A flat surface

was used to immobilize the sawbone and to standardize the evaluation of the rotation. Retroversion was defined as negative value, anteversion was defined as positive value. All parameters were evaluated on PACS (Picture Archiving and Communication System) radiologic system.

A formula was created to calculate that how many degrees the plates should be placed to obtain desired amount of rotation. Depending on the length and angle of the plates, the arc length scanned by the plate was equal to the arc length scanned by the distal fragment until the plate became horizontally. Additionally, the arc length scanned by the distal fragment depended on its radius. The length of the arc (the distance between the first position (B) and the last position (B') of the distal screw of the medial plate) swept by the plate is equal to the path drawn by the rotation around its axis of the distal region (Figure 4). The virtually spiral movement of this region along the axis is shown as the progress of

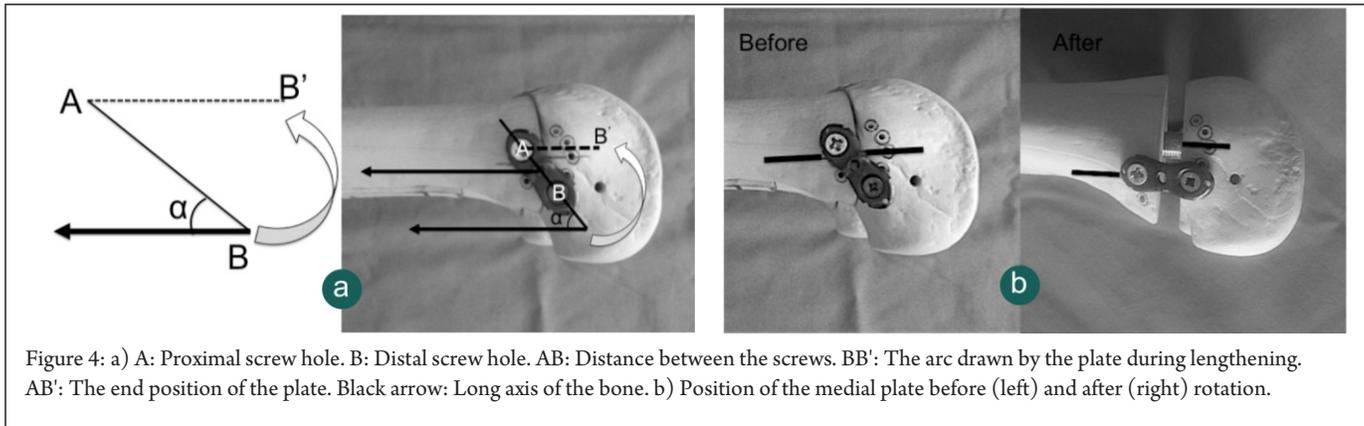


Figure 4: a) A: Proximal screw hole. B: Distal screw hole. AB: Distance between the screws. BB': The arc drawn by the plate during lengthening. AB': The end position of the plate. Black arrow: Long axis of the bone. b) Position of the medial plate before (left) and after (right) rotation.

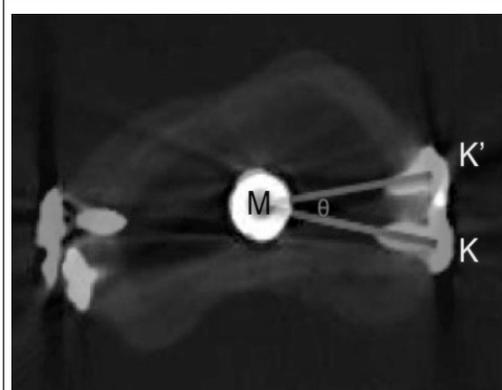


Figure 5:- Two superimposed tomographic sections of the distal region of the bone (before and after rotation). M: Center of the distal region of the bone. K: Starting point of the rotation. K': End point of the rotation. MK=MK': Radius of the distal region of the bone. θ : Rotation angle.

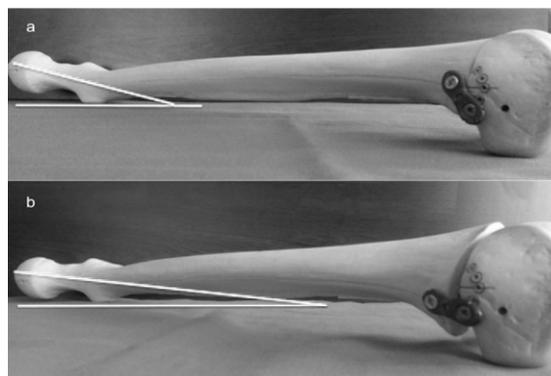


Fig. 6: a) The image before lengthening, b) The image after lengthening (the external rotation of the distal fragment led to decrease in anteversion of the sawbone).

were 90° when the α angles were 50° and 36° and aPDFA was 91° when the α angle was 26°.

The distance between the screw holes (AB) was 18 mm, and the radius of the distal fragment of the femur (MK) was 35 mm. When the formula was used, the amounts of correction (θ) were 25.7°, 18.5°, and 13.4°, respectively. None of the calculated degrees of correction were comparable to the CT measurements.

Discussion

Angular deformities around the knee can be corrected with

hemiepiphysodeses in skeletally immature patients [2,6,7]. The epiphysis grows symmetrically under normal conditions. If the physal plate is compressed from one side, an angular deformity can occur. Mechanical modulation of longitudinal growth by compressive forces is a widely accepted notion, also known as the Volkmann's law [8]. However, osteotomy is the most commonly used surgical technique for the correction of rotational deformities of the long bones. Furthermore, rotational guided growth are not currently used to correct rotational deformities of the long bones in clinical practise.

There are two reported animal studies [4,5]. Arami et al used rabbit femur in their study and to induce external rotation the distal part of the medial plate was positioned posteriorly and to induce internal rotation the distal part of the medial plate was positioned anteriorly. They said that because of the shape of the medial femoral condyle, some technical difficulties occurred

the arc on the surface of the cylinder (Figure 5). A full rotation of the arc of the helix is equal to the diagonal line of the open shape of the cylinder.

The formula which was created to calculate the amount of correction (θ) is demonstrated as follows:

$$\frac{BB'}{2\pi \cdot AB \cdot \alpha / 360} = \frac{KK'}{2\pi \cdot MK \cdot \theta / 360} = \frac{BB'KK'}{2\pi \cdot AB \cdot \alpha / 360 \cdot 2\pi \cdot MK \cdot \theta / 360} = \theta \cdot AB \cdot \alpha / MK$$

(A: Position of the proximal screw of the medial plate, B: The first position of the distal screw of the medial plate, B': The last position of the distal screw of the medial plate, α : The angle between long axis of the sawbone and medial plate, M: Center of the distal region of the bone. K: Starting point of the rotation. K': End point of the rotation. MK=MK': Radius of the distal region of the bone. θ : Rotation angle)

Results

The FL was 421.79 mm and the anteversion of the sawbone was 8.26° before distraction.

When the sawbone was distracted, rotation of the distal fragment was observed without translation (Figure 6). When the angles between the plates and the long axis of the bone (α) were 50°, 36°, and 26°, the axial rotations were -11.25°, 2.43°, and 7.06° respectively on CT and the FLs were 433.38mm, 430.02mm, 429.74mm respectively after full distraction. Thus, the amount of correction (θ) were 19.25°, 5.83°, and 1.20°, respectively. The wider the angle between the plates and the long axis of the bone, the more rotation and lengthening occurred. As the screws were not tightened completely, rotation of the plates, which led to more rotation of the distal fragment and lengthening of the bone, occurred more easily.

In the coronal plane, mL DFA was 87° before lengthening. After lengthening mLDFAs were constant when the α angle were 50° and 36°. But mL DFA was 83° when the α was 26°.

In the sagittal plane, aPDFA was 89° before lengthening. After lengthening aPDFAs

and medial plate was placed in desired position in the group of external rotation [4]. The physal line of the distal femur of rabbit is wavy and not straight. For this reason to place both plates obliquely in different directions on wavy line is not seen feasible. Firstly more straight physal line is needed. Cobanoglu et al studied on the proximal tibial epiphysis of rabbit to induce external rotation. The reason why they preferred proximal tibia to distal femur could be that the proximal tibia had straighter physal line than distal femur. They only studied on external rotation group and did not create a formula about prediction amount of rotation [5]. This study is a biomechanical study. And the aim of this study is to create a formula based on the angle between the long axis of the bone and the plates. A distal femoral physal plate was created by cutting the sawbone just above the trochlear sulcus and two 8-plates were placed on either side of the cutting line. It was thought that if two plates were placed at reverse angles to each other on either side of the bone, the distal fragment would be rotated. According to this theory, the screws in the holes should not be tightened completely to create rotation points or free zones between the plates and screws. These rotation points would cause the plates to spin around the screws like a hinge. The screws were placed as closely as possible to the cutting line, and thus the plate placement angle was increased. We used an intramedullary device to distract the

bone. While the sawbone was being distracted, rotation of the distal fragment was obtained and this led to a reduction in the anteversion of the femur due to the placement of the plates. The upper limit of rotation which can be corrected, is due to orientation of the plates and the distance between the proximal and the distal screws. Therefore, insertion of these plates with the greatest angle to the long axis as possible and the greatest distance between the screws as possible will lead greater rotation. These are two important variables in the formula. These variables are related to anatomical properties of the bone such as width and points for plate fixation. The angle between the positions of the plate and the bone axis needs monitoring. For this reason, the position of the plates at the end of the rotational correction is crucial to prevent angular deformities. The important points of this technique are the distance between the proximal and distal screws and the tightness of the screws. The use of long plates results in greater lengthening and rotation, depending on the distance between the holes. When the distance between the proximal and distal screws is as great as possible, increased gap between the fragments and more rotation of the distal fragment are observed. And to be able to obtain rotation of the plate more easily, the screws must not be tightened completely. Another important point is that placement of the plates at the same angle onto the

bone. For this reason, the amount of rotation will reveal according to the plate having less angle with bone axis. When the axis of this plate is parallel to the bone axis, the plate will not rotate and causes a deformity. So the deformities of the condyles can affect the rotational measure. Arami et al used inter-plate angle in their study and declared that every 1° of change in this angle corresponded 0.378° of rotational profile difference [4]. In our opinion because of the reasons mentioned above, the rotational profile is dependent on the angle between the plate and bone axis, not inter-plate angle. The CT measurements and calculations using the formula differed from each other. There are three possible reasons for this disparity: First, there was laxity between the screws and the plates, leading to instability between the proximal and distal regions of the sawbone. Second, the sawbone had a circular structure whereas the plates were straight. These incompatible shapes might prevent rotation. Third, the distal region of the bone does not form a precise circle. This technique has not been performed to humans yet. This biomechanical study supports that this technique can be used for the correction of rotational deformities of the long bones. It's said that the wider angle between the plates and the long axis of the bone, the greater rotation. But further animal studies are required to demonstrate efficacy of this hypothesis.

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